

دری در الکتروستاتیک کلاسیک (۱)

Maxwell
معادلات M تحت تبدیل
بسیار در دسترس

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \cdot \vec{E} = 4\pi\rho$$

$$\vec{\nabla} \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{j}$$

$$\vec{B}(\vec{x}, t)$$

$$\vec{E}(\vec{x}, t)$$

$$\rho(\vec{x}, t)$$

$$\vec{j}(\vec{x}, t)$$

معادله پواسون

$$\frac{d}{dt} \int d^3x \rho = \dot{Q} = 0$$

$$\leftrightarrow \frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{j} = 0$$

$$\int d^3x \frac{\partial \rho}{\partial t} + \int d^3x \vec{\nabla} \cdot \vec{j} = 0$$

$$\frac{\partial}{\partial t} \underbrace{\int d^3x \rho}_{Q} = 0$$

$$m \ddot{\vec{x}} = q \left(\vec{E} + \frac{1}{c} \vec{v} \times \vec{B} \right) = \vec{F}_L \quad q = -e$$

نیروی لورنتس

$$\vec{A}(\vec{x}, t)$$

$$\varphi(\vec{x}, t)$$

$$\rightarrow \begin{cases} \vec{\nabla} \cdot \vec{B} = 0 \\ \vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0 \end{cases} \rightarrow \begin{cases} \vec{B} = \vec{\nabla} \times \vec{A} \\ \vec{\nabla} \times \left(\vec{E} + \frac{1}{c} \frac{\partial \vec{A}}{\partial t} \right) = 0 \end{cases} \Rightarrow$$

$$\vec{\nabla} \times \vec{A} = \vec{B}$$

$$\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \vec{\nabla} \varphi$$

تبدیل گالیلئو

$$\begin{cases} \vec{A}'(\vec{x}, t) = \vec{A}(\vec{x}, t) + \vec{\nabla} f \\ \varphi'(\vec{x}, t) = \varphi(\vec{x}, t) - \frac{1}{c} \frac{\partial f}{\partial t} \end{cases}$$

میدان نفاصی تحت تبدیل گالیلئو

$$\vec{B}' = \vec{\nabla} \times \vec{A}' \stackrel{!}{=} \vec{\nabla} \times \vec{A} = \vec{B}$$

$$\vec{B}' = \vec{\nabla} \times \vec{A}' = \vec{\nabla} \times (\vec{A} + \vec{\nabla} f) = \vec{\nabla} \times \vec{A} + \underbrace{\vec{\nabla} \times \vec{\nabla} f}_{=0} = \vec{B}$$

میدان الکتروستاتیک تحت تبدیل گالیلئو

$$\vec{E}' = -\vec{\nabla} \varphi' - \frac{1}{c} \frac{\partial \vec{A}'}{\partial t} \stackrel{!}{=} -\vec{\nabla} \varphi - \frac{1}{c} \frac{\partial \vec{A}}{\partial t} = \vec{E}$$

در بیان کرنی

$$\vec{\nabla} \cdot \vec{A} = 0, \quad \frac{\partial \varphi}{\partial t} = 0$$

$$\begin{aligned} 1) \quad \vec{\nabla} \cdot \vec{E} = 4\pi\rho &\Rightarrow + \Delta \varphi = -4\pi\rho \\ 2) \quad \vec{\nabla} \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{j} &\Rightarrow \Delta \vec{A} - \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} = \frac{4\pi}{c} \vec{j} \end{aligned}$$

۱) اثبات

$$\vec{\nabla} \cdot \left(-\vec{\nabla} \varphi - \frac{1}{c} \frac{\partial \vec{A}}{\partial t} \right) = 4\pi\rho$$

$$-\Delta \varphi - \frac{1}{c} \frac{\partial}{\partial t} \underbrace{\vec{\nabla} \cdot \vec{A}}_{=0} = 4\pi\rho \Rightarrow \Delta \varphi = -4\pi\rho$$

۲) اثبات

$$\partial_\mu A^\mu = 0$$

در بیان لورنتس

$$\vec{\nabla} \cdot \vec{A} + \frac{1}{c} \frac{\partial \varphi}{\partial t} = 0$$

$$\Rightarrow \vec{\nabla} \cdot \vec{A} = -\frac{1}{c} \frac{\partial \varphi}{\partial t}$$

$$\vec{\nabla} \cdot \vec{E} = -\Delta \varphi - \frac{1}{c} \frac{\partial}{\partial t} \vec{\nabla} \cdot \vec{A} = 4\pi\rho$$

1) اثبات

$$\Rightarrow \nabla \cdot \vec{A} = -\frac{1}{c} \frac{\partial \varphi}{\partial t}$$

$$\nabla \cdot \vec{E} = -\Delta \varphi - \frac{1}{c} \frac{\partial}{\partial t} \nabla \cdot \vec{A} = 4\pi \rho$$

$$\Delta \varphi - \frac{1}{c^2} \frac{\partial^2 \varphi}{\partial t^2} = -4\pi \rho$$

Aharonov-Bohm Effect

اثر آهارونوف-بوهم
 سوانت حرکت یک ذره باردار (انرژی) در حضور میدان الکترومغناطی در فضایی که پتانسیل آن صفر است.

$$L = L(\vec{x}, \dot{\vec{x}}; t) = T - U$$

$$= \frac{1}{2} m \dot{\vec{x}}^2 - q \varphi(\vec{x}, t) + \frac{q}{c} \vec{A}(\vec{x}, t) \cdot \dot{\vec{x}}$$

سوانت اولی که پتانسیل آن صفر است

$$\frac{\partial L}{\partial x_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}_i} = 0$$

$$\frac{\partial L}{\partial x_i} = -q \partial_i \varphi + \frac{q}{c} \partial_i A_j \dot{x}_j$$

$$\frac{\partial L}{\partial \dot{x}_i} = m \dot{x}_i + \frac{q}{c} A_i \rightarrow m \ddot{x}_i + \frac{q}{c} \frac{d}{dt} A_i = \frac{d}{dt} \frac{\partial L}{\partial \dot{x}_i}$$

$$\frac{d}{dt} A_i = \frac{\partial}{\partial t} A_i + \dot{x}_j \partial_j A_i \quad \vec{A}(\vec{x}, t)$$

$$-q \partial_i \varphi + \frac{q}{c} \partial_i A_j v_j = m \ddot{x}_i + \frac{q}{c} \left(\frac{\partial}{\partial t} A_i + v_j \partial_j A_i \right)$$

$$m \ddot{x}_i = +q \left(\underbrace{-\partial_i \varphi - \frac{1}{c} \frac{\partial}{\partial t} A_i}_{+E_i} \right) + \frac{q}{c} v_j \left(\underbrace{\partial_i A_j - \partial_j A_i}_{F_{ij}} \right)$$

$$F_{ij} = \partial_i A_j - \partial_j A_i = \epsilon_{ijk} B_k$$

$$\begin{pmatrix} 0 & B_x & -B_y \\ -B_x & 0 & B_z \\ +B_y & -B_z & 0 \end{pmatrix} = \vec{F}$$

$$\frac{q}{c} v_j \epsilon_{ijk} B_k = \frac{q}{c} (\vec{v} \times \vec{B})_i$$

$$m \ddot{\vec{x}} = q \vec{E} + \frac{q}{c} (\vec{v} \times \vec{B})$$

$$H\psi = E\psi$$

در فضای همیلتون

$$L = L(\vec{x}, \dot{\vec{x}}; t)$$

$$H = H(\vec{x}, \vec{p}; t)$$

$$[\hat{x}_i, \hat{p}_j] = i\hbar \delta_{ij}$$

$$\frac{\partial L}{\partial x_i} = p_i$$

$$\frac{\partial H}{\partial x_i} = -\dot{p}_i$$

$$\frac{\partial H}{\partial p_i} = \dot{x}_i$$

$$H = \frac{\vec{p}^2}{2m} + V(\vec{x})$$

$$\frac{\partial H}{\partial x_i} = -\dot{p}_i = -\partial_i V$$

$$\left. \begin{aligned} \frac{\partial H}{\partial x_i} &= -\dot{p}_i = -\partial_i V \\ \frac{\partial H}{\partial p_i} &= \dot{x}_i = \frac{p_i}{m} \end{aligned} \right\} \rightarrow \ddot{x}_i = \frac{\dot{p}_i}{m} \Rightarrow \ddot{x}_i = -\frac{\partial_i V}{m}$$

$$m \ddot{x}_i = -\partial_i V = F_i$$

$$m \ddot{\vec{x}} = -\vec{\nabla} V = \vec{F}$$

$$H = \frac{1}{2m} \left(\vec{p} - \frac{e}{c} \vec{A} \right)^2 + e\varphi$$

$$1) \frac{\partial H}{\partial x_i} = -\dot{p}_i$$

$$2) \frac{\partial H}{\partial p_i} = \dot{x}_i$$

$$1) \frac{\partial H}{\partial x_i} = -\frac{e}{c} \frac{1}{m} \left(\vec{p} - \frac{e}{c} \vec{A} \right)_j \partial_i A_j + e \partial_i \varphi = -\dot{p}_i$$

$$2) \frac{\partial H}{\partial p_i} = \frac{1}{m} \left(\vec{p} - \frac{e}{c} \vec{A} \right)_i = \dot{x}_i$$

$$1) \frac{\partial H}{\partial x_i} = -\dot{p}_i = -\frac{e}{c} v_j \partial_i A_j + e \partial_i \varphi$$

$$\dot{x}_i = \frac{1}{m} \left(p_i - \frac{e}{c} A_i \right) \rightarrow m \ddot{x}_i = \dot{p}_i - \frac{e}{c} \frac{d}{dt} A_i$$

$$= \dot{p}_i - \frac{e}{c} \frac{\partial}{\partial t} A_i - \frac{e}{c} v_j \partial_j A_i$$

$$m \ddot{x}_i = \frac{e}{c} v_j \partial_i A_j - e \partial_i \varphi - \frac{e}{c} \frac{\partial}{\partial t} A_i - \frac{e}{c} v_j \partial_j A_i$$

$$= e \left(-\partial_i \varphi - \frac{1}{c} \frac{\partial}{\partial t} A_i \right) + \frac{e}{c} v_j \left(\partial_i A_j - \partial_j A_i \right)$$

$$= e E_i + \frac{e}{c} v_j \epsilon_{ijk} B_k \quad F_{ij} = \epsilon_{ijk} B_k$$

$$m \ddot{\vec{x}} = e \vec{E} + \frac{e}{c} \vec{v} \times \vec{B} = \vec{F}_L$$

گزارش

$$\hat{H} = \frac{1}{2m} \left(\hat{\vec{p}} - \frac{e}{c} \hat{\vec{A}}(\vec{x}) \right)^2 + e \hat{\varphi}(\vec{x})$$

$$\psi(\vec{x}, t) \rightsquigarrow \hat{H} \psi(\vec{x}) = E \psi(\vec{x})$$

$$e^{\frac{i}{\hbar} E t} \quad \hat{\vec{p}} = \frac{\hbar}{i} \vec{\nabla}_{\vec{x}}$$

$$\hat{\vec{x}} = \vec{x} \quad \left. \begin{aligned} \hat{\vec{A}}(\vec{x}) &= \vec{A}(\vec{x}) \\ \hat{\varphi}(\vec{x}) &= \varphi(\vec{x}) \end{aligned} \right\}$$

$$\left(\frac{1}{2m} \left(\frac{\hbar}{i} \vec{\nabla} - \frac{e}{c} \vec{A}(\vec{x}) \right)^2 + e \varphi(\vec{x}) \right) \psi(\vec{x}) = E \psi(\vec{x})$$